

Talon Robot Manual

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Talon Robot Manual

Fouad Sabry



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Handbook of Virtual Environments Kelly S. Hale, Kay M. Stanney, 2014-09-10 A Complete Toolbox of Theories and Techniques The second edition of a bestseller Handbook of Virtual Environments Design Implementation and Applications presents systematic and extensive coverage of the primary areas of research and development within VE technology It brings together a comprehensive set of contributed articles that address the

Humanoid Robot Fouad Sabry, 2025-01-02 Humanoid Robot is a comprehensive exploration into the world of robotics offering insights into the groundbreaking technologies ethical considerations and design innovations that shape humanoid robots Whether you re a professional student or enthusiast this book delves into the intricate relationship between humanity and robots blending theory with practice for those eager to understand this rapidly advancing field

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2 Robot A broad overview of robots their classifications and the pivotal role they play in modern industries and society

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5 Passive dynamics This chapter examines passive dynamics in robotics where robots move with minimal energy input to simulate natural motion

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Fouad Sabry,2025-01-22 In the rapidly advancing world of robotics understanding the interplay between mobile systems and manipulators is key to shaping the future of automation from industries to healthcare Mobile Manipulator by Fouad Sabry offers an indepth exploration of this critical field presenting cuttingedge technologies and theoretical frameworks that will benefit professionals students enthusiasts and anyone interested in the evolving landscape of robotics science Chapters Brief Overview 1 Mobile manipulator Explore the integration of mobility and manipulation in robotics the foundation of versatile autonomous systems 2 Robot Delve into the essential components and classifications of robots setting the stage for more complex robotic systems 3 Mobile robot Understand the design and functionality of robots capable of movement essential for dynamic task execution in varied environments 4 Selfreconfiguring modular robot Learn about robots that can change their structure to adapt to different tasks expanding their utility 5 Virtual fixture Discover how virtual fixtures assist robots in performing precise complex tasks blending software and hardware seamlessly 6 Adaptable robotics Investigate robots designed for adaptability crucial for evolving needs in unpredictable environments 7 Agricultural robot Examine the role of robots in modernizing agriculture from harvesting to crop monitoring enhancing productivity 8 Cyber physical system Understand the integration of physical systems with computational algorithms forming the backbone of advanced robotic systems 9 Gerd Hirzinger Gain insight into Gerd Hirzinger s contributions to robotics including innovations in space robotics and manipulator technology 10 Robotics A comprehensive overview of robotics exploring foundational concepts and ongoing innovations in the field 11 Opensource robotics Learn about the opensource movement in robotics empowering creators and accelerating the pace of innovation globally 12 Cobot Explore collaborative robots designed to work alongside humans enhancing productivity while ensuring safety 13 MiroSurge Study the MiroSurge system an innovative platform for minimally invasive surgery blending robotics and healthcare 14 Robotnik Automation Discover Robotnik s contributions to industrial automation from design to implementation of robotic solutions 15 Masakatsu Fujie Investigate the work of Masakatsu Fujie a leader in flexible and adaptive robotic systems pushing the boundaries of robotic technology 16 Oussama Khatib Understand the pioneering work of Oussama Khatib in humanrobot interaction including developments in robotics for realworld applications 17 Cloud robotics Explore how cloud computing is transforming robotics enabling access to data processing

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Mobile Manipulator is a mustread for professionals seeking to stay ahead in robotics as well as for students and enthusiasts aiming to build a strong understanding of this dynamic field Its interdisciplinary approach not only offers technical knowledge but also engages with the ethical social and practical aspects of robotics

Robot Fouad Sabry, 2025-01-27

Robot a comprehensive work in the Robotics Science series by Fouad Sabry explores the fascinating world of robotics offering insights into both the technical and conceptual aspects of this rapidly advancing field Whether you are a professional student or enthusiast this book is an invaluable resource that covers fundamental principles and cuttingedge developments With a clear focus on applications history and future trends Robot provides essential knowledge that will enhance your understanding and spark your curiosity about the robotics revolution The book is ideal for anyone seeking to dive deep into the science behind robotics from basic concepts to futuristic possibilities

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Autonomous aircraft This chapter covers the future of autonomous aircraft focusing on their potential in both commercial and military sectors UGV Interoperability Profile Discover how the UGV interoperability profile standardizes communication across different robotic platforms THeMIS Understand the THeMIS autonomous vehicle designed for military logistics and support pushing the boundaries of robotic utility Integrated Unmanned Ground System A study of the integrated systems that combine autonomous ground vehicles with human teams for effective operations Brave1 Learn about the BRAVE1 autonomous vehicle engineered for complex terrains providing valuable insights into autonomous vehicle design

Autonomous Research Robot Fouad Sabry, 2024-12-18 1 Autonomous Research Robot This chapter introduces the core principles of autonomous research robots laying the foundation for the book 2 Lidar Learn how Lidar technology plays a crucial role in navigation and perception for autonomous systems 3 Autonomous Robot Delve into the structure and function of autonomous robots examining key components and their interdependencies 4 Robotic Mapping Understand how robots create and interpret maps of their environment for efficient navigation and task completion 5 Simultaneous Localization and Mapping Explore the crucial process of simultaneous localization and mapping SLAM that allows robots to navigate unknown areas 6 PatrolBot A case study of PatrolBot a robot designed for security applications demonstrating practical implementation 7 Unmanned Ground Vehicle Investigate the design and function of unmanned ground vehicles emphasizing their military and commercial applications 8 Stanley vehicle Learn about Stanley the autonomous vehicle that won the 2005 DARPA Grand Challenge and its engineering breakthroughs 9 Automated Guided Vehicle Discover how automated guided vehicles are transforming industries like logistics and manufacturing 10 Mobile Robot Explore the evolution of mobile robots and their impact on automation in various fields 11 Positioning System Understand the importance of positioning systems in robotics ensuring precise location tracking for autonomous operations 12 Player Project An introduction to the Player Project which offers software for robot control and simulation 13 Indoor Positioning System Learn how indoor positioning systems enhance robots ability to navigate in complex indoor environments 14 Robot Navigation Dive into the algorithms and technologies that allow robots to navigate effectively and autonomously 15 Webots Explore Webots a simulation platform that supports the development and testing of autonomous robots 16 Mobile Robot Programming Toolkit Understand the tools and techniques used to program mobile robots enhancing their autonomy and functionality 17 Inertial Navigation System Learn how inertial navigation systems allow robots to maintain accurate positioning without external references 18 Willow Garage Explore the contributions of Willow Garage to the development of opensource software and hardware for robotics 19 CajunBot A look at CajunBot a unique robot project with applications in academic research and development 20 National Robotics Engineering Center Discover the innovations coming from the National Robotics Engineering Center a leader in autonomous robot development 21 Alcherio Martinoli Learn about the contributions of Alcherio Martinoli to the field of multirobot systems and autonomous research

Mobile Robot Fouad Sabry, 2024-05-04 What is Mobile Robot A mobile

robot is an automatic machine that is capable of locomotion Mobile robotics is usually considered to be a subfield of robotics and information engineering How you will benefit I Insights and validations about the following topics Chapter 1 Mobile robot Chapter 2 Robot Chapter 3 Autonomous robot Chapter 4 Robot control Chapter 5 Swarm robotics Chapter 6 Wireless sensor network Chapter 7 Teleoperation Chapter 8 Unmanned ground vehicle Chapter 9 Obstacle avoidance Chapter 10 Robot navigation II Answering the public top questions about mobile robot III Real world examples for the usage of mobile robot in many fields Who this book is for Professionals undergraduate and graduate students enthusiasts hobbyists and those who want to go beyond basic knowledge or information for any kind of Mobile Robot *Hexapod Robotics* Fouad Sabry, 2025-01-27 Discover the fascinating world of Hexapod Robotics and the limitless possibilities it offers for advancing robotics technology This book is an essential resource for anyone passionate about exploring innovative walking mechanisms and bioinspired designs within the broader context of Robotics Science Whether you re a professional a student or simply an enthusiast this book provides indepth insights that far outweigh its cost offering invaluable knowledge and practical applications that can shape future innovations Chapters Brief Overview 1 Hexapod robotics Explore sixlegged robots unique stability and versatility in mobility 2 Walking Delve into the dynamics and engineering of walking in robotic systems 3 Gait Understand different gait patterns and their applications in robotic locomotion 4 BEAM robotics Learn about minimalist robotics driven by bioinspired engineering principles 5 Snakebot Examine the serpentine motion of robots navigating tight spaces 6 Robot locomotion Gain insights into the various methods of robotic movement and control 7 Mobile robot Investigate the challenges and designs of autonomous mobile robots 8 Terrestrial locomotion Study robots that mimic landbased animals for efficient movement 9 Bow leg Discover how flexible leg structures enhance robot agility 10 Tripedalism Uncover the mechanics behind threelegged robot motion 11 Selfreconfiguring modular robot See how robots adapt to environments by changing form 12 Adaptable robotics Focus on robots capable of adjusting to dynamic conditions 13 Legged robot Examine robots that leverage legs for maneuvering over complex terrain 14 Rhex Understand the design and utility of this resilient hexapod robot 15 Robotics Explore the broader field of robotics and its transformative impact 16 LAURON Study this hexapod robot s applications in research and exploration 17 Bioinspired robotics Delve into robotics inspired by nature s designs 18 Walking vehicle Explore vehicles that walk rather than roll for enhanced mobility 19 Insectoid robot Investigate robots mimicking insect locomotion for efficiency 20 Bipedalism Analyze the challenges of creating robots that walk on two legs 21 Quadrupedalism Learn about fourlegged robots stability and speed advantages This book provides a treasure trove of knowledge that helps bridge theory and practical robotics empowering readers to innovate and excel in this ever evolving field Join the journey of exploring cuttingedge technologies and unleash the potential of robotic advancements Ballbot Fouad Sabry, 2025-01-24 Explore the cuttingedge world of robotics with Ballbot a compelling addition to the Robotics Science series This book unravels the intricate dynamics of robotics combining theoretical

foundations and practical insights Whether you re a professional a student or a hobbyist Ballbot provides unparalleled value inspiring innovation and advancing your understanding of robotics Chapters Brief Overview 1 Ballbot Introduction to ballbots and their unique balancing mechanisms 2 Humanoid robot Examines humanoid designs and their alignment with human interaction 3 LeJOS Overview of this Javabased robotics programming platform 4 Motion control Principles of motion control for precision and stability 5 Mobile robot Study of mobile robots and their autonomous navigation capabilities 6 Six degrees of freedom Understanding movement freedom in robotics applications 7 Underactuation Discusses systems with fewer actuators than degrees of freedom 8 Lego Mindstorms NXT Insights into educational robotics through LEGO systems 9 Adaptable robotics Adaptability in robotics for dynamic environments 10 Legged robot Focus on legged locomotion for varied terrains 11 Spherical robot Explores spherical designs for smooth versatile movement 12 URBI Overview of the Universal Realtime Behavior Interface in robotics 13 Webots Introduction to this 3D simulation environment for robotics 14 Robotics Holistic insights into the interdisciplinary field of robotics 15 Surena robot Case study on Iran s humanoid robot Surena 16 Oussama Khatib Contributions of a leading robotics researcher to the field 17 Juggling robot Exploration of robotics in juggling and dynamic tasks 18 Highperformance positioning system Advanced positioning for precision robotics 19 Continuum robot Study of flexible robots with continuous structures 20 Robot A deep dive into the essence of robots across applications 21 Domo robot Examination of the assistive robot Domo in human interaction This book is your gateway to mastering robotics core concepts and groundbreaking advancements Each chapter builds a comprehensive narrative that bridges foundational knowledge with cuttingedge research Ballbot is a mustread for anyone eager to excel in robotics and shape the future of this transformative field

Robotic Mapping Fouad Sabry, 2024-12-28 Unlock the future of robotics with Robotic Mapping a definitive guide that explores the critical aspects of robot navigation mapping and control This book is designed for professionals students and enthusiasts who are passionate about robotics science Whether you are a researcher in mobile robotics or a hobbyist eager to understand cuttingedge technologies this book provides invaluable insights It is more than just a resource it s an investment in your robotic knowledge Chapters Brief Overview 1 Robotic mapping Explore the foundational concepts behind how robots create and interpret maps of their environment 2 Autonomous robot Learn how robots operate independently making decisions without human intervention 3 Simultaneous localization and mapping Delve into the key algorithms that enable robots to map their surroundings and determine their location simultaneously 4 Swarm robotics Understand how multiple robots can work together to achieve complex tasks through collaborative behavior 5 Navigation mesh Discover the structure that allows robots to move efficiently through virtual environments 6 Denning Mobile Robot Company Study the role of industry leaders in shaping the future of mobile robotics 7 Gregory Dudek Learn from the expert whose work has profoundly influenced the field of robotics and autonomous systems 8 Mobile robot Examine the mechanics and design behind mobile robots that navigate realworld environments 9 Motion planning Investigate the

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Robotics and Artificial Intelligence Class 9 (A.Y. 2023-24)Onward Hema Dhingra,2023-05-20 The concept of Robotics and Artificial Intelligence AI has been in practice over the years with the advent of technological progress overtime and is transforming our world in profound and unprecedented ways with the potential to revolutionise virtually every aspect of our lives From self driving cars and personal assistants to medical diagnosis and financial forecasting AI is rapidly becoming an indispensable tool for solving complex problems and unlocking new opportunities for innovation and progress As the world becomes increasingly complex and interconnected robotics has emerged as a critical field that is revolutionising how we live work and interact with our environment From manufacturing and transportation to healthcare and education robots are transforming industries and creating new opportunities for innovation and progress Keeping this in mind I C S E Robotics and Artificial Intelligence for Class 9 has been designed This book is strictly based on the latest syllabus prescribed by the Council for the Indian School Certificate Examination CISCE and is intended to provide a comprehensive overview of the field exploring the fundamental principles and applications of robotics and AI technology Based on the latest research and developments in the fields this book offers a detailed overview of the key concepts and techniques that underpin AI from machine learning and natural language processing to computer vision and Robotics This book will provide you with a comprehensive and up todate understanding of these exciting and rapidly evolving fields keeping in line with ICSE syllabus

Salient Features of this Book As per the latest syllabus and examination pattern prescribed by the ICSE The book is divided into two parts Part I deals with the Robotics portion This part consists of three units Introduction to Robotics Robot as a System and Concepts in Robotics Part II deals with the Artificial Intelligence portion This part consists of two units Introduction to Artificial Intelligence AI Role of Data and Information Evolution of Computing Introduction to Data and Programming with Python AI Concepts and AI Project Framework and Assignments and Laboratory Experiments All the concepts explained in a simple language using a step by step approach supported by a Lot of illustrations Chapter wise Features Learning Objectives introduces you to the learning outcomes and knowledge criteria covered in the chapter Chapter content caters to know about the topic of the chapter which may enrich your knowledge Did You Know provides an interesting piece of knowledge to get the students interested Activity encourages students to integrate theory with practice Recap sums up the key concepts given in the chapter Key Terms are the main terminologies that are present in the chapter Each chapter contains an accompanying exercise that will assess students understanding after they have completed the entire unit by answering the questions given in the exercise Online Support E books for teachers only Teachers Resource Book Overview of the chapters Lesson plan Answers of the exercise We hope that this book will inspire you to explore the limitless possibilities of Robotics and AI to make meaningful contributions to this dynamic and transformative field Thus it is a request to our esteemed readers to share the feedback suggestions etc for the improvement of the book All your suggestions for the improvement of the book are welcome Author

Recent Advances in Systems, Control and Information Technology Roman Szewczyk, Małgorzata Kaliczyńska, 2016-11-29 This book presents the proceedings of the International Conference on Systems Control and Information Technologies 2016 It includes research findings from leading experts in the fields connected with INDUSTRY 4.0 and its implementation especially intelligent systems advanced control information technologies industrial automation robotics intelligent sensors metrology and new materials Each chapter offers an analysis of a specific technical problem followed by a numerical analysis and simulation as well as the implementation for the solution of a real world problem

Remote Control Vehicle Fouad Sabry, 2025-01-29 Explore the captivating world of remotecontrolled vehicles in Remote Control Vehicle a comprehensive guide within the Robotics Science series This book is an essential resource for professionals students and enthusiasts alike diving into the cuttingedge technology that powers various unmanned systems Whether you're seeking to enhance your knowledge or fuel your passion for robotics this book offers invaluable insights that far outweigh its cost Chapters Brief Overview 1 Remotecontrol vehicle Delve into the fundamentals of remotecontrol technology 2 Unmanned aerial vehicle Discover the evolution and applications of drones in various fields 3 Remote control Understand the core principles and mechanisms of remote control systems 4 Robot control Explore advanced techniques for manipulating robotic systems remotely 5 Radio control Learn about the radio frequencies that enable seamless communication 6 Remotely operated underwater vehicle Examine the technology behind underwater

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Beat the Odds Survival Manual Tim MacWelch,2020-10-06 The New York Times bestselling author teaches practical strategies for maximizing your chances no matter how unlikely the crisis This fast paced yet level headed survival guide from the author of Prepare for Anything breaks down the odds of facing dozens of scary situations from the fairly likely like getting lost in the woods to the unlikely but terrifying being hit by an asteroid attacked by zombies or other sci fi worthy scenarios It then provides concrete strategies for improving your odds of survival Each danger is rated with handy graphics that give an at a glance idea of how likely it is to happen how much you should worry about it and how possible it is to survive if it happens to you In the pages that follow survival expert Tim MacWelch gives step by step instructions tutorials and hints to help you beat the odds and live to tell the tale

Automated Guided Vehicle Fouad Sabry,2025-01-24 In a world where automation and robotics are revolutionizing industries Automated Guided Vehicle stands as a crucial resource for understanding the dynamics of this transformation This book not only caters to professionals but also to undergraduate and graduate students enthusiasts and hobbyists eager to delve into the world of robotics Through comprehensive insights and practical applications readers will discover the immense value of mastering automated guided vehicle systems making the investment in this book far more rewarding than its cost Chapters Brief Overview 1 Automated guided vehicle Explores the fundamentals and applications of automated guided vehicles 2 Robot Discusses the evolution and roles of robots in modern automation 3 Logistics Analyzes the critical impact of robotics on logistics efficiency 4 Forklift Examines the integration of robotics into forklift operations 5 Semiautomatic command to line of sight Details the principles behind semiautomatic operations 6

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By immersing yourself in this book you will unlock the secrets to harnessing the power of automation and robotics paving the way for innovation in your field Don t miss out on this opportunity to elevate your understanding and skills in robotics science

Living Robotics Fouad Sabry, 2024-12-09

1 BEAM robotics Explore the fundamental principles driving bioinspired autonomous robots 2 Embedded system Understand the backbone tech enabling control in complex robotics applications 3 Mark Tilden Discover the mind behind BEAM robotics and his revolutionary robotics approach 4 Behaviorbased robotics Delve into robots designed to exhibit lifelike behavioral responses 5 Heliostat Learn about robotic heliostats and their role in solar energy applications 6 Solarroller Study solarpowered BEAM robots with dynamic energyefficient designs 7 Crawler BEAM Analyze BEAM crawlers and their movement inspired by biological organisms 8 Analog robot Examine analogcontrolled robots and their streamlined circuitry 9 Mobile robot Understand the technology behind autonomous movementfocused robots 10 HERO robot Get insights into HERO s role in educational and developmental robotics 11 Brosl Hasslacher Uncover the contributions of Brosl Hasslacher to BEAM robotics 12 Stiquito Explore Stiquito the versatile insectlike robot used in educational settings 13 RS Media Learn about RS Media the multimedia robot that brings interactive experiences 14 Roboquad Discover Roboquad s fourlegged design balancing stability with flexibility 15 Webots Dive into Webots a simulator tool that advances robot research and design 16 Braitenberg vehicle Investigate these unique robots that mimic cognitive responses 17 IISc Guidance Control and Decision Systems Laboratory Overview the lab s pioneering research in autonomous robotics 18 Elmer and Elsie robots Examine the early robot prototypes that led to behaviorbased robotics 19 Microprocessor Understand the microprocessor s crucial role in robotics control and function 20 Microcontroller Explore microcontrollers that provide essential computing power for robots 21 AVR microcontrollers Review the AVR family integral to many modern robotics applications

Swarm Robotics Fouad

Sabry,2022-08-09 What Is Swarm Robotics An approach to the coordination of several robots as a system swarm robotics is characterized by its use of a large number of fairly straightforward physical robots It is a subfield of swarm robotics It is hypothesized that the interactions between the robots as well as the interactions of the robots with their surroundings will lead to the emergence of the desired collective behavior This method originated in the realm of artificial swarm intelligence as well as the biological studies of insects ants and other natural domains that exhibit swarm behavior How You Will Benefit I Insights and validations about the following topics Chapter 1 Swarm robotics Chapter 2 Autonomous robot Chapter 3 Unmanned aerial vehicle Chapter 4 Flocking behavior Chapter 5 Swarm behaviour Chapter 6 Boids Chapter 7 Micro air vehicle Chapter 8 Swarm intelligence Chapter 9 Multi agent system Chapter 10 Robert C Michelson Chapter 11 Mobile robot Chapter 12 Autonomous logistics Chapter 13 IISc Guidance Control and Decision Systems Laboratory Chapter 14 Uncrewed vehicle Chapter 15 Autonomous aircraft Chapter 16 Roland Siegwart Chapter 17 Swarm robotic platforms Chapter 18 List of unmanned aerial vehicle applications Chapter 19 Swarm 3D printing Chapter 20 Drones in wildfire management Chapter 21 Margarita Chli II Answering the public top questions about swarm robotics III Real world examples for the usage of swarm robotics in many fields IV 17 appendices to explain briefly 266 emerging technologies in each industry to have 360 degree full understanding of swarm robotics technologies Who This Book Is For Professionals undergraduate and graduate students enthusiasts hobbyists and those who want to go beyond basic knowledge or information for any kind of swarm robotics

Learning Applied to Ground Vehicles Fouad Sabry,2024-05-05 What is Learning Applied to Ground Vehicles The Learning Applied to Ground Vehicles LAGR initiative which was in operation from 2004 until 2008 was designed with the intention of expediting the development of autonomous perception based off road navigation in robotic unmanned ground vehicles UGVs DARPA which is a research agency under the Department of Defense of the United States of America provided funding for LAGR How you will benefit I Insights and validations about the following topics Chapter 1 DARPA LAGR Program Chapter 2 DARPA Chapter 3 Autonomous robot Chapter 4 Military robot Chapter 5 DARPA Grand Challenge Chapter 6 Unmanned ground vehicle Chapter 7 European Land Robot Trial Chapter 8 Mobile robot Chapter 9 Crusher robot Chapter 10 National Robotics Engineering Center II Answering the public top questions about learning applied to ground vehicles III Real world examples for the usage of learning applied to ground vehicles in many fields Who this book is for Professionals undergraduate and graduate students enthusiasts hobbyists and those who want to go beyond basic knowledge or information for any kind of Learning Applied to Ground Vehicles **Unmanned Ground Vehicle** Fouad Sabry,2024-06-18

What is Unmanned Ground Vehicle An unmanned ground vehicle UGV is a vehicle that operates while in contact with the ground without an onboard human presence UGVs can be used for many applications where it is inconvenient dangerous expensive or impossible to use an onboard human operator Typically the vehicle has sensors to observe the environment and autonomously controls its behavior or uses a remote human operator to control the vehicle via teleoperation How you will

benefit I Insights and validations about the following topics Chapter 1 Unmanned ground vehicle Chapter 2 DARPA Chapter 3 Autonomous robot Chapter 4 Military robot Chapter 5 Micro air vehicle Chapter 6 Foster Miller TALON Chapter 7 Mobile robot Chapter 8 TerraMax Chapter 9 Gladiator Tactical Unmanned Ground Vehicle Chapter 10 Black Knight vehicle II Answering the public top questions about unmanned ground vehicle Who this book is for Professionals undergraduate and graduate students enthusiasts hobbyists and those who want to go beyond basic knowledge or information for any kind of Unmanned Ground Vehicle

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