# ME6712 - MECHATRONICS LABORATORY

#### OBJECTIVES

To know the method of programming the microprocessor and also the design, modelling & analysis of basic electrical, hydraulic & pneumatic Systems which enable the students to understand the concept of mechatronics.

#### LIST OF EXPERIMENTS

- Assembly language programming of 8085 Addition Subtraction -Multiplication - Division - Sorting - Code Conversion.
- Stepper motor interface.
- 3. Traffic light interface.
- 4. Speed control of DC motor.
- 5. Study of various types of transducers.
- Study of hydraulic, pneumatic and electro-pneumatic circuits.
- Modelling and analysis of basic hydraulic, pneumatic and electrical circuits using Software.
- B. Study of PLC and its applications.
- 9. Study of image processing technique.

#### OUTCOMES

Upon completion of this course, the students can able to design Mechatronics system with the help of Microprocessor, PLC and other electrical and Electronics Circuits.

#### LIST OF EQUIPMENT FOR A BATCH OF 30 STUDENTS

5.NO	NAME OF THE EQUIPMENT	Qty
1	Basic Pneumatic Trainer Kit with manual and electrical controls/ PLC Control.	1.
22	Basic Hydraulic Trainer Kit	1
34.	Hydraulics and Pneumatics Systems Simulation Software	1.0
4.	8051 - Microcontroller kit with stepper motor and drive circuit sets	2
5	Image processing system with hardware & software	1
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# **Thth Sem Lab Manual For Mechatronics**

**Michael Brown** 

#### **Thth Sem Lab Manual For Mechatronics:**

Embedded Computing and Mechatronics with the PIC32 Microcontroller Kevin Lynch, Nicholas Marchuk, Matthew Elwin, 2015-12-08 For the first time in a single reference this book provides the beginner with a coherent and logical introduction to the hardware and software of the PIC32 bringing together key material from the PIC32 Reference Manual Data Sheets XC32 C Compiler User's Guide Assembler and Linker Guide MIPS32 CPU manuals and Harmony documentation This book also trains you to use the Microchip documentation allowing better life long learning of the PIC32 The philosophy is to get you started quickly but to emphasize fundamentals and to eliminate magic steps that prevent a deep understanding of how the software you write connects to the hardware Applications focus on mechatronics microcontroller controlled electromechanical systems incorporating sensors and actuators To support a learn by doing approach you can follow the examples throughout the book using the sample code and your PIC32 development board. The exercises at the end of each chapter help you put your new skills to practice Coverage includes A practical introduction to the C programming language Getting up and running quickly with the PIC32 An exploration of the hardware architecture of the PIC32 and differences among PIC32 families Fundamentals of embedded computing with the PIC32 including the build process time and memory efficient programming and interrupts A peripheral reference with extensive sample code covering digital input and output counter timers PWM analog input input capture watchdog timer and communication by the parallel master port SPI I2C CAN USB and UART An introduction to the Microchip Harmony programming framework Essential topics in mechatronics including interfacing sensors to the PIC32 digital signal processing theory of operation and control of brushed DC motors motor sizing and gearing and other actuators such as stepper motors RC servos and brushless DC motors For more information on the book and to download free sample code please visit http www nu32 org Extensive freely downloadable sample code for the NU32 development board incorporating the PIC32MX795F512H microcontroller Free online instructional videos to support many of the chapters **Digital Transformation in Education and Artificial** Intelligence Application Daniel Vasić, Emil Brajković, 2025-10-09 This book constitutes the proceedings of the Third International Conference on Digital Transformation in Education and Artificial Intelligence Applications MoStart 2025 held in Mostar Bosnia and Herzegovina during April 23 25 2025 The 19 full papers were presented in this volume were carefully reviewed and selected from 39 submissions They focus on advanced educational technology intelligent systems robotics in education security within Industry 4 0 frameworks the implementation of large language models in personalized learning environments and broader cross disciplinary applications of AI IEEE/ASME International Conference on Advanced Intelligent Mechatronics Proceedings, 2005 IEEE/CHMT International Electronic Manufacturing Technology Symposium .1992 Issues in Education by Subject, Profession, and Vocation: 2013 Edition, 2013-05-01 Issues in Education by Subject Profession and Vocation 2013 Edition is a ScholarlyEditions book that delivers timely authoritative and

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Mechatronics with Experiments Sabri Cetinkunt,2014-11-11 Comprehensively covers the fundamental scientific principles and technologies that are used in the design of moderncomputer controlled machines and processes Covers embedded microcontroller based design of machines Includes MATLAB Simulink based embedded controlsoftware development Considers electrohydraulic motion control systems withextensive applications in construction equipment industry Discusses electric motion control servo systems and coordinated multi axis automated motion control forfactory automation applications Accompanied by a website hosting a solution manual Introduction to Mechatronics

Laboratory Excercises David G. Alciatore, Michael B. Histand, 2003-05-01 Provides students and professionals with a resource for project and lab work for electromechanical systems The 15 experiments included in this work cover a range of subjects from basic instrumentation and measurement to use of microcontrollers and accelerometers It includes a general equipment list Laboratory Exercises in Merchatronics Musa Jouaneh, 2012-02-10 This book contains mechatronics laboratory exercises designed to give the student hands on experience with applications of the concepts covered in a mechatronics course 14 laboratory exercises are included plus a section that has a list of suggested extended or final projects. The first six laboratory exercises are designed to illustrate basic measurements electrical circuits and electronic concepts

Later exercises focus on microcontrollers timing and state transition diagrams sensors stepper motors and feedback control *The Mechatronics Handbook - 2 Volume Set* Robert H. Bishop,2018-10-08 The first comprehensive reference on mechatronics The Mechatronics Handbook was quickly embraced as the gold standard in the field From washing machines to coffeemakers to cell phones to the ubiquitous PC in almost every household what these days doesn t take advantage of mechatronics in its design and function In the scant five years since the initial publication of the handbook the latest generation of smart products has made this even more obvious Too much material to cover in a single volume Originally a single volume reference the handbook has grown along with the field The need for easy access to new material on rapid changes in technology especially in computers and software has made the single volume format unwieldy The second edition is offered as two easily digestible books making the material not only more accessible but also more focused Completely

revised and updated Robert Bishop's seminal work is still the most exhaustive state of the art treatment of the field available

**Essentials of Mechatronics** John Billingsley, 2006-05-11 Learn how to study analyze select and design a successful mechatronic product This innovative cutting edge publication presents the essential nature of mechatronics a field at the crossroads of information technology and mechanical and electrical engineering Readers learn how to blend mechanisms electronics sensors control strategies and software into a functional design Given the breadth that the field of mechatronics draws upon this publication provides a critical service to readers by paring down the topics to the most essential ones A common thread throughout the publication is tailoring performance to the actual needs of the user rather than designing by the book Practical methods clarify engineering trade offs needed to design and manufacture competitive state of the art products and systems Key features include Easy to construct set of laboratory experiments to give readers practice in controlling difficult systems using discrete time algorithms Essentials of control theory concentrating on state space and easily constructed simulations in JavaScript including typical mechatronic systems with gross nonlinearities where linear methods give the wrong answer Hot topics that include advances in the automotive multimedia robotics defense medical and consumer industries Author provided Web site at www EssMech com offers additional resources including videos dynamic simulation examples software tools and downloads There are hundreds of choices involved in all but the simplest of mechatronic design tasks Using this publication as a reference electrical mechanical and computer designers and engineers can find the most efficient cost effective methods to transform their goals into successful commercial products With its use of laboratory experiments this publication is also recommended as a graduate level textbook Author Web site located at www EssMech com provides in depth support material that includes links to simulations for modeling dynamic systems with real time interactions image processing examples and 3D robot modeling software enabling readers to construct and manipulate their own mechanism as well as other useful links Mechanical Engineering Laboratory Manual Earl Baldwin Smith, 1912

Familiarization ,2014 Mechatronic Systems, Sensors, and Actuators Robert H. Bishop,2017-07-28 This book covers

the key elements of physical systems modeling sensors and actuators signals and systems computers and logic systems and software and data acquisition It describes mathematical models of the mechanical electrical and fluid subsystems that comprise many mechatronic systems

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