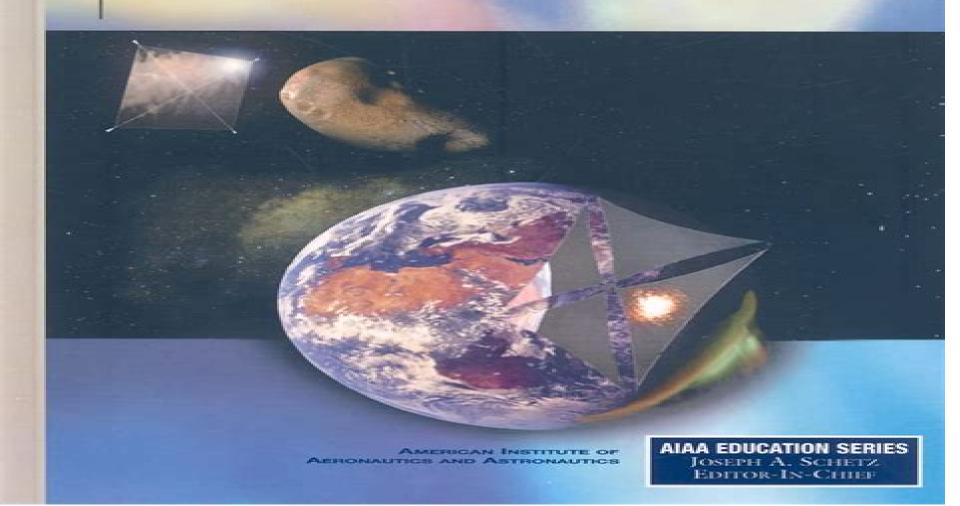
SPACE VEHICLE DYNAMICS AND CONTROL SECOND EDITION

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Marshall H. Kaplan

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transfer functions is the way to design and tune feedback loops around the embedded model state predictor control law reference generator The design versus the uncertainty class is driven by analytic stability and performance inequalities The method is applied to several attitude and orbit control problems The book begins with an extensive introduction to attitude geometry and algebra and ends with the core themes state space dynamics and Embedded Model Control Fundamentals of orbit attitude and environment dynamics are treated giving emphasis to state space formulation disturbance dynamics state feedback and prediction closed loop stability Sensors and actuators are treated giving emphasis to their dynamics and modelling of measurement errors Numerical tables are included and their data employed for numerical simulations Orbit and attitude control problems of the European GOCE mission are the inspiration of numerical exercises and simulations The suite of the attitude control modes of a GOCE like mission is designed and simulated around the so called mission state predictor Solved and unsolved exercises are included within the text and not separated at the end of chapters for better understanding training and application Simulated results and their graphical plots are developed through MATLAB Simulink code

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Control Applications of Vehicle Dynamics Jingsheng Yu, Vladimir Vantsevich, 2021-12-24 This book presents essential knowledge of car vehicle dynamics and control theory with NI LabVIEW software product application resulting in a practical yet highly technical guide for designing advanced vehicle dynamics and vehicle system controllers Presenting a clear overview of fundamental vehicle dynamics and vehicle system mathematical models the book covers linear and non linear design of model based controls such as wheel slip control vehicle speed control path following control vehicle stability and rollover control stabilization of vehicle trailer system Specific applications to autonomous vehicles are described among the methods It details the practical applications of Kalman Bucy filtering and the observer design for sensor signal estimation

alongside lateral vehicle dynamics and vehicle rollover dynamics. The book also discusses high level controllers alongside a clear explanation of basic control principles for regenerative braking in both electric and hybrid vehicles and wheel torque vectoring systems Concrete LabVIEW simulation examples of how the models and controls are used in representative applications along with software algorithms and LabVIEW block diagrams are illustrated It will be of interest to engineering students automotive engineering students and automotive engineers and researchers Dynamics and Control of Flexible Navigation and Tracking in Space: Analysis and Algorithms Sanat K. Space Vehicles Peter W. Likins, 1970 Biswas, 2023-12-31 This book focuses on the navigation and tracking of artificial space objects with emphasis on modelling the dynamics in a wide range of space missions including earth orbiting satellite missions launch and re entry missions as well as interplanetary missions. The book guides you in designing suitable estimation algorithms for each type of mission. It also helps you in addressing non linearity in designing navigation algorithms for space missions and walks you through the process for choosing estimators for navigation and tracking of space vehicles You ll find specific details on earth orbiting satellite tracking and navigation that helps you determine precise orbit and will understand how to get navigation and tracking results using the Least Square Estimation and the Extended Kalman Filter EKF for simulated observations You also learn how to address tracking performance of spacecraft in interplanetary trajectories that are affected by a diverse set of problems such low signal power intermittent observations observations at low rate and delays Techniques for designing navigation and tracking algorithms to address these problems are delineated The book also provides in depth coverage of multi object tracking relevant data association and estimation algorithms in the Situational Space Awareness context MATLAB Simulink based software is provided for simulation and simulated data set This is an excellent reference and practical tool for professionals in the field of Guidance Navigation and Control along with researchers and advanced students in the field of space vehicle navigation tracking guidance and control NASA Technical Memorandum ,1978 Guidance. Navigation, and Control for Spacecraft Rendezvous and Docking: Theory and Methods Yongchun Xie, Changging Chen, Tao Liu, Min Wang, 2021-02-16 This book focuses on the theory and design methods for guidance navigation and control GNC in the context of spacecraft rendezvous and docking RVD The position and attitude dynamics and kinematics equations for RVD are presented systematically in accordance with several different coordinate systems including elliptical orbital frame and recommendations are supplied on which of these equations to use in different phases of RVD The book subsequently explains the basic principles and relative navigation algorithms of RVD sensors such as GNSS radar and camera type RVD sensors It also provides guidance algorithms and schemes for different phases of RVD including the latest research advances in rapid RVD In turn the book presents a detailed introduction to intelligent adaptive control and proposes corresponding theoretical approaches to thruster configuration and control allocation for RVD Emphasis is placed on the design method of active and passive trajectory protection in different phases of RVD and on the safety design of the RVD mission as a whole For purposes

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