A novel method of unmanned surface vehicle autonomous cruise

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Abstract

Purpose — This paper aims to propose a new method for combining global path planning with local path planning, to provide an efficient solution for unmanned surface webside (USV) path planning despite the changeable environment. Path planning is the key issue of USV navigation. A lot of research works were done on the global and local path planning. However, little attention was given to combining global path planning with local path planning.

Design/methodology/approach — A search of shortcut Dijkstra algorithm was used to control the USV in the global path planning. When the USV encounters unknown obstacles, it switches to our modified artificial potential field (APF) algorithm for local path planning. The combinatorial method improves the approach of USV path planning in complex environment.

Findings — The method in this paper offers a solution to the issue of path planning in changeable or unchangeable environment, and was confirmed by simulations and experiments. The USV follows the global path based on the search of shortcut Dijkstra algorithm. Both USV achieves obstacle avoidances in the local region based on the modified APF algorithm after obstacle detection. Both the simulation and experimental results demonstrate that the combinatorial path planning method is more efficient in the complex environment.

Originality/value - This paper proposes a new path planning method for USV in changeable environment. The proposed method is capable of efficient navigation in changeable and unchangeable environment.

Keywords Navigation, Path planning, Autonomous robots, USV, Dijkstra

Paper type Research paper

1. Introduction

Over the past several decades, unmanned surface vehicle technology has been greatly improved with the advance of computer capabilities (Han et al., 2015). It attracted much attention for their ability to perform dangerous and time-consuming missions for military and civilian purposes such as environmental monitoring, survey and inspection of marine structures after natural disasters or large-scale accidents (Murphy et al., 2011).

To perform these missions using unmanned surface vehicle (USV), autonomous navigation is a central capability, as USV can move between a starting point and a target point without human intervention (Tamm and Bucknall, 2013). Robot navigation involves solving the path planning or obstacle avoidance problem to generate a feasible path and to optimize this path with respect to certain criteria (Gu and Cao, 2011; Kim et al., 2014). Obstacle avoidance is consisted of global

obstacle avoidance and local obstacle avoidance, and the problem of autonomous obstacle avoidance has been studied intensively in the past (Markus et al., 2014; Chen et al., 2013).

For local path planning, different algorithms bring different effect of obstacle avoidance in unknown environment. Artificial potential field (APF) is a typical path-planning algorithm for robots (Khatib, 1986). Although it is very suitable for low-level real-time control of robot due to its explicit physical implication and simple mathematical description (Zhang et al., 2010; Shu et al., 2014), there are still some problems in the original algorithm, and some substantial improvements were made. Bacterial potential field, which improves the APF with Bacterial evolutionary algorithm (Meetiel et al., 2015; Byrne et al., 2014; Petris et al., 2012), ensures a feasible, optimal and safe path. For dynamic obstacles, Liu and Bocknall (2015) presented the novel

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Unmanned Dan Fesperman, 2015-06-23 From the widely acclaimed author of The Prisoner of Guant name and The Double Game an electrifying timely psychologically gripping descent into the hidden expanding world of drone warfare Timely and disturbing An exciting story expertly told The Washington Post Book World As an F 16 fighter pilot Darwin Cole was a family man on top of his world Now he s a washout drunk living alone in a trailer in the Nevada desert Haunted by what he saw on the display of the Predator drone he piloted an Afghan child running for her life he reluctantly joins three journalists seeking to discover the identity of the anonymous and possibly roque intelligence operative who called the shots in his last ill fated mission On the trail of this operative Cole and his new allies will discover the dark heart of our surveillance culture with connections to intelligence to the military and to the unchecked private contractors who stand to profit richly from the advancing technology technology not just for use over there but for right here right now Advanced UAV Aerodynamics, Flight Stability and Control Pascual Marqués, Andrea Da Ronch, 2017-04-19 Comprehensively covers emerging aerospace technologies Advanced UAV aerodynamics flight stability and control Novel concepts theory and applications presents emerging aerospace technologies in the rapidly growing field of unmanned aircraft engineering Leading scientists researchers and inventors describe the findings and innovations accomplished in current research programs and industry applications throughout the world Topics included cover a wide range of new aerodynamics concepts and their applications for real world fixed wing airplanes rotary wing helicopter and quad rotor aircraft The book begins with two introductory chapters that address fundamental principles of aerodynamics and flight stability and form a knowledge base for the student of Aerospace Engineering The book then covers aerodynamics of fixed wing rotary wing and hybrid unmanned aircraft before introducing aspects of aircraft flight stability and control Key features Sound technical level and inclusion of high quality experimental and numerical data Direct application of the aerodynamic technologies and flight stability and control principles described in the book in the development of real world novel unmanned aircraft concepts Written by world class academics engineers researchers and inventors from prestigious institutions and industry The book provides up to date information in the field of Aerospace Engineering for university students and lecturers aerodynamics researchers aerospace engineers aircraft designers and manufacturers Wave and Tidal Energy Carlos Guedes Soares, Matthew Lewis, 2020-06-25 Concerns relating to energy supply and climate change have driven renewable energy targets around the world Marine renewable energy could make a significant contribution to reducing greenhouse gas emissions and mitigating the consequences of climate change while providing a high technology industry. The conversion of wave and tidal energy into electricity has many advantages Individual tidal and wave energy devices have been installed and proven with commercial arrays planned throughout the world The wave and tidal energy industry has developed rapidly in the past few years therefore it seems timely to review current research and map future challenges Methods to improve understanding of the

resource and interactions between energy extraction the resource and the environment are considered such as resource characterisation including electricity output design considerations e g extreme and fatigue loadings and environmental impacts at all timescales ranging from turbulence to decadal and all spatial scales from device and array scales to shelf sea The Cambridge History of the American Novel Leonard Cassuto, Clare Virginia Eby, Benjamin Reiss, 2011-03-24 scales This ambitious literary history traces the American novel from its emergence in the late eighteenth century to its diverse incarnations in the multi ethnic multi media culture of the present day In a set of original essays by renowned scholars from all over the world the volume extends important critical debates and frames new ones Offering new views of American classics it also breaks new ground to show the role of popular genres such as science fiction and mystery novels in the creation of the literary tradition. One of the original features of this book is the dialogue between the essays highlighting cross currents between authors and their works as well as across historical periods While offering a narrative of the development of the genre the History reflects the multiple methodologies that have informed readings of the American novel and will change the way scholars and readers think about American literary history Hirell. A Novel John Saunders (Novelist.).1872 Proceedings of the International Conference on Artificial Intelligence and Computer Vision (AICV2021) Aboul Ella Hassanien, Abdelkrim Hagig, Peter J. Tonellato, Ladjel Bellatreche, Sam Goundar, Ahmad Taher Azar, Essaid Sabir, Driss Bouzidi, 2021-05-28 This book presents the 2nd International Conference on Artificial Intelligence and Computer Visions AICV 2021 proceeding which took place in Settat Morocco from June 28 to 30 2021 AICV 2021 is organized by the Scientific Research Group in Egypt SRGE and the Computer Networks Mobility and Modeling Laboratory IR2M Hassan 1st University Faculty of Sciences Techniques Settat Morocco This international conference highlighted essential research and developments in the fields of artificial intelligence and computer visions The book is divided into sections covering the following topics Deep Learning and Applications Smart Grid Internet of Things and Mobil Applications Machine Learning and Metaheuristics Optimization Business Intelligence and Applications Machine Vision Robotics and Speech Recognition Advanced Machine Learning Technologies Big Data Digital Transformation AI and Network Analysis Cybersecurity Feature Selection Classification and Applications Advances in Maritime Technology and Engineering Carlos Guedes Soares, Tiago A. Santos, 2024-05-08 Advances in Maritime Technology and Engineering comprises a collection of the papers presented at the 7th International Conference on Maritime Technology and Engineering MARTECH 2024 held in Lisbon Portugal on 14 16 May 2024 This Conference has evolved from the series of biannual national conferences in Portugal which have become an international event reflecting the internationalization of the maritime sector and its activities MARTECH 2024 is the seventh of this new series of biannual conferences This book comprises 142 contributions that were reviewed by an International Scientific Committee Advances in Maritime Technology and Engineering is dedicated to maritime transportation ports as well as maritime safety and reliability It further comprises sections dedicated to ship design

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Autonomous Revolution: Strategies, Threats and Challenges Umair B. Chaudhry, Hamid Jahankhani, 2025-07-24
This book offers a comprehensive dive into the rapidly evolving world of autonomous vehicles and their pivotal role in modern data collection and mission critical operations From unmanned vehicles UVs navigating complex urban landscapes to traversing remote environments the integration of advanced algorithms and cloud based infrastructure enables real time data acquisition and processing Topics covered include resilient navigation systems bio inspired evolution for safer collaboration and the crucial governance and security challenges facing land air and sea based UVs Additionally the book explores emerging threats such as cyber physical vulnerabilities counter drone technologies and the need for secure Flying Ad Hoc Networks FANETs The future of UVs is further examined through the lens of quantum computing pushing the boundaries of autonomous navigation and decision making By compiling these scattered and essential topics into one resource this book serves as a vital reference for professionals researchers and policymakers seeking to understand and shape the future of autonomous systems

Advancements in Smart Computing and Information Security Sridaran

Rajagopal, Parvez Faruki, Kalpesh Popat, 2023-01-10 This two volume constitutes the refereed proceedings of the First International Conference on Advancements in Smart Computing and Information Security ASCIS 2022 held in Rajkot India in November 2022 The 37 full papers and 19 short papers presented were thoroughly reviewed and selected from the 206 submissions The papers are organized in topical sections on artificial intelligence smart computing cyber security industry

Advanced Autonomous Vehicle Design for Severe Environments V.V. Vantsevich, M.V. Blundell, 2015-10-20 Classical vehicle dynamics which is the basis for manned ground vehicle design has exhausted its potential for providing novel design concepts to a large degree At the same time unmanned ground vehicle UGV dynamics is still in its infancy and is currently being developed using general analytical dynamics principles with very little input from actual vehicle dynamics theory This technical book presents outcomes from the NATO Advanced Study Institute ASI Advanced Autonomous Vehicle Design for Severe Environments held in Coventry UK in July 2014 The ASI provided a platform for world class professionals to meet and discuss leading edge research engineering accomplishments and future trends in manned and unmanned ground vehicle dynamics terrain mobility and energy efficiency The outcomes of this collective effort serve as an analytical foundation for autonomous vehicle design Topics covered include historical aspects pivotal accomplishments and the analysis of future trends in on and off road manned and unmanned vehicle dynamics terramechanics soil dynamic characteristics uncertainties and stochastic characteristics of vehicle environment interaction for agile vehicle dynamics modeling new methods and techniques in on line control and learning for vehicle autonomy fundamentals of agility and severe environments mechatronics and cyber physics issues of agile vehicle dynamics to design for control energy harvesting and cyber security and case studies of agile and inverse vehicle dynamics and vehicle systems design including optimisation of suspension and driveline systems. The book targets graduate students who desire to advance further in leading edge vehicle dynamics topics in manned and unmanned ground vehicles PhD students continuing their research work and building advanced curricula in academia and industry and researchers in government agencies and private companies **AI and Robotics Applications** in Disaster Response Menka Chopra, 2025-01-24 AI and Robotics Applications in Disaster Response explores the innovative use of artificial intelligence and robotics in managing emergency situations We discuss how AI driven tools and robotic systems can aid search and rescue missions risk assessment and disaster recovery operations. The book highlights real world case studies including the use of drones for disaster mapping and robots for hazardous material handling We also address the ethical implications and challenges of deploying AI in critical situations This book is an essential guide for emergency responders policymakers and technology enthusiasts aiming to leverage AI and robotics for disaster management

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diagrams and practical principle simulation examples in the frequency band from 100 MHz to 18 GHz or even 60 GHz Starting with RF signals the book progressively examines various signal bands such as VLF LF MF HF VHF UHF L S C X Ku and K and the corresponding geolocation requirements per band and per application to achieve required performance objectives of up to 0o precision Part II follows a step by step approach of RF geolocation techniques and concludes with notes on state of the art geolocation designs as well as advanced features found in signal generator instruments Drawing upon years of practical experience and using numerous examples and illustrative applications Ilir Progri provides a comprehensive introduction to Geolocation of RF Signals and includes hands on real world labs and applications using MATLAB in the areas of RF signals specifications RF geolocation distributed wireless communications networks and RF geolocation Geolocation of RF Signals Principles and Simulations will be of interest to government agency program managers industry professionals and engineers academic researchers faculty and graduate students who are interested in or currently designing developing and deploying innovative geolocation of RF Signal systems Issues in Electronic Circuits, Devices, and Materials: 2013 Edition ,2013-05-01 Issues in Electronic Circuits Devices and Materials 2013 Edition is a ScholarlyEditions book that delivers timely authoritative and comprehensive information about Microwave Research The editors have built Issues in Electronic Circuits Devices and Materials 2013 Edition on the vast information databases of ScholarlyNews You can expect the information about Microwave Research in this book to be deeper than what you can access anywhere else as well as consistently reliable authoritative informed and relevant The content of Issues in Electronic Circuits Devices and Materials 2013 Edition has been produced by the world's leading scientists engineers analysts research institutions and companies All of the content is from peer reviewed sources and all of it is written assembled and edited by the editors at ScholarlyEditions and available exclusively from us You now have a source you can cite with authority confidence and credibility More information is available at http www ScholarlyEditions com Cleveden. [A Novel.] Stephen Yorke (pseud. [i.e. Mary Linskill.]),1876

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Distributed Computer and Communication Networks: Control, Computation, Communications Vladimir M. Vishnevskiy, Konstantin E. Samouylov, Dmitry V. Kozyrev, 2021-12-14 This book constitutes the refereed post conference proceedings of the 24th International Conference on Distributed and Computer and Communication Networks DCCN 2021 held in Moscow Russia in September 2021 The 26 revised full papers and 3 revised short papers were carefully reviewed and selected from 151 submissions The papers cover the following topics computer and communication networks analytical modeling of distributed systems and distributed systems applications

Advances in Visual Computing George Bebis, Richard Boyle, Bahram Parvin, Darko Koracin, Fatih Porikli, Sandra Skaff, Alireza Entezari, Jianyuan

Min, Daisuke Iwai, Amela Sadagic, Carlos Scheidegger, Tobias Isenberg, 2016-12-09 The two volume set LNCS 10072 and LNCS 10073 constitutes the refereed proceedings of the 12th International Symposium on Visual Computing ISVC 2016 held in Las Vegas NV USA in December 2016 The 102 revised full papers and 34 poster papers presented in this book were carefully reviewed and selected from 220 submissions The papers are organized in topical sections Part I LNCS 10072 comprises computational bioimaging computer graphics motion and tracking segmentation pattern recognition visualization 3D mapping modeling and surface reconstruction advancing autonomy for aerial robotics medical imaging virtual reality computer vision as a service visual perception and robotic systems and biometrics Part II LNCS 9475 applications visual surveillance computer graphics and virtual reality Engineering Psychology and Cognitive Ergonomics Don Harris, 2009-07-15 The 13th International Conference on Human Computer Interaction HCI Inter tional 2009 was held in San Diego California USA July 19 24 2009 jointly with the Symposium on Human Interface Japan 2009 the 8th International Conference on Engineering Psychology and Cognitive Ergonomics the 5th International Conference on Universal Access in Human Computer Interaction the Third International Conf ence on Virtual and Mixed Reality the Third International Conference on Internati alization Design and Global Development the Third International Conference on Online Communities and Social Computing the 5th International Conference on Augmented Cognition the Second International Conference on Digital Human Mod ing and the First International Conference on Human Centered Design A total of 4 348 individuals from academia research institutes industry and gove mental agencies from 73 countries submitted contributions and 1 397 papers that were judged to be of high scientific quality were included in the program These papers dress the latest research and development efforts and highlight the human aspects of the design and use of computing systems The papers accepted for presentation thoroughly cover the entire field of human computer interaction addressing major advances in knowledge and effective use of computers in a variety of application areas Enter the Drones Bill Carey, 2016-07-28 How unmanned aerial vehicles proven in war were introduced in the US for peaceful purposes A narrative history covering the FAA's early experiences with UAVs to the present day While drones have become controversial recently US federal agencies have used them since the 1990s

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