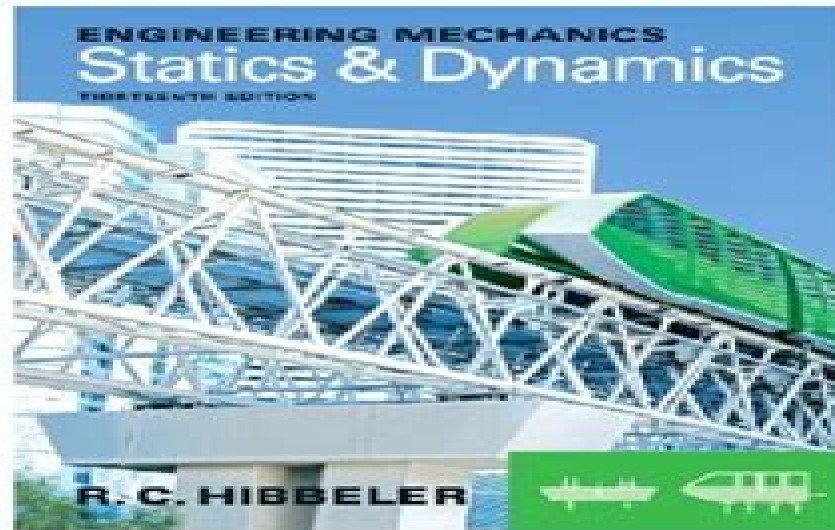


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latter does not have a full solution because the handbooks comprise simplified parameters that cannot be used for an exact solution Chapter 4 offers mathematical model for the arbitrary disposition of the spinning object in space that shows the action of the additional four inertial torques acting on the third axis and new dependencies of gyroscope motions Chapter 7 now presents mathematical model for the gyroscope nutation with a full solution The known mathematical model presents a partial solution due to the complexity of the problem Stress, Strain, and Structural Dynamics Bingen Yang,2022-09-13

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de desarrollar una comprensi n amplia y b sica de la cinem tica de los mecanismos Est dirigido a profesionales y estudiantes de ingenier a como un referente que indica a trav s de diferentes ejercicios desarrollados alternativas para el an lisis de mecanismos En el primer cap tulo y en la primera parte de los dem s se hace un breve an lisis de los fundamentos necesarios para abordar las tres metodolog as de an lisis Adem s en la parte final del primer cap tulo se hace una presentaci n de los mecanismos analizados cinem ticamente en los cap tulos subsiguientes Con el m todo gr fico del segundo cap tulo se hace una presentaci n b sica para el an lisis cinem tico de mecanismos en una posici n particular Este m todo adem s se utiliza como referencia para validar los resultados de otras metodolog as como la vectorial o de n mero complejo presentadas en los cap tulos 3 y 4 El an lisis vectorial del cap tulo 3 hace uso de vectores para representar las posiciones las velocidades y las aceleraciones as como para representar relaciones de direcci n y sentido entre distintos elementos del mecanismo De forma similar al cap tulo 3 en el cap tulo 4 se emplean n meros complejos para representar las magnitudes vectoriales simplificando el c lculo de las cantidades involucradas Para finalizar en el cap tulo 5 se presenta el uso de las herramientas computacionales MATLAB o GNU Octave para programar los modelos matem ticos desarrollados en los cap tulos 3 y 4 y establecer el comportamiento de un mecanismo en funci n de las condiciones de entrada Los resultados obtenidos en este cap tulo son validados mediante el uso del m todo gr fico del cap tulo 2 En general este texto sobre cinem tica de mecanismos planos proporciona una base te rica y pr ctica para comprender c mo se mueven y posicionan los componentes de un mecanismo utilizando herramientas anal ticas y gr ficas para el estudio de sistemas mec nicos

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