

UNIT I - CLASSIFICATION OF SIGNALS AND SYSTEMS**1. Define Continuous time step function and Delta function.**

A step function is defined as

$$u(t) = \begin{cases} 1 & t \geq 0 \\ 0 & t < 0 \end{cases}$$

A delta function is defined as

$$\delta(t) = \begin{cases} 1 & t = 0 \\ 0 & t \neq 0 \end{cases}$$

2. Define energy and power signals.(Apr/May 2015) (Nov/Dec 2015)

The energy of a signal $x(t)$ is defined as

$$E = \int_{-\infty}^{\infty} |x(t)|^2 dt$$

A signal $x(t)$ is called an energy signals if the energy is finite and power is zero.

The average power of a signal $x(t)$ is defined as

$$P = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} |x(t)|^2 dt$$

A Signal $x(t)$ is called a power signal if the average power is finite and Energy is infinite.

3. Verify whether $x(t) = A e^{-\alpha t} u(t)$ is an energy signal or not

This signal is non periodic and of infinite duration .It can be an energy signal.

$$\begin{aligned} E &= \int_{-\infty}^{\infty} |x(t)|^2 dt \\ &= \int_0^{\infty} [Ae^{-\alpha t}]^2 dt \quad \text{Since } u(t) = 1 \text{ for } 0 \leq t \leq \infty \\ &= A^2 \int_0^{\infty} e^{-2\alpha t} dt \\ &= A^2 \left[\frac{e^{-2\alpha t}}{-2\alpha} \right]_0^{\infty} = \frac{A^2}{2\alpha} \end{aligned}$$

The energy is finite and non zero; hence the signal is energy signal

Signals And Systems 16 Marks With Answers

Atul P. Godse, Dr. Deepali A. Godse



Signals And Systems 16 Marks With Answers:

Signals and Systems Dr. J. S. Chitode, 2021-01-01 Analysis of signals is given in first chapter Types of signals properties of systems are also presented Second chapter presents Fourier series analysis Its properties are also discussed Fourier transform is given in third chapter along with its properties The transmission of signals through linear systems is given in fourth chapter Realizability and distortion less transmission is also discussed Fifth chapter discusses convolution its properties and impulse response properties of LTI systems Causality and stability are discussed Autocorrelation and cross correlation is also given Energy spectral density and power spectral density along with their properties are also given Sampling principles and types are given in sixth chapter Chapter seventh and eighth presents Laplace transforms and z transforms in detail Their properties inversion and applications to LTI systems are analyzed in detail Relationships among transforms are also given All the concepts are supported with lot of solved examples *Communication Systems - I* Dr. J. S.

Chitode, 2020-12-01 Analysis tools such as Fourier series Fourier transforms signals systems and spectral densities are discussed in the second chapter Introduction is presented in the first chapter Third chapter presents additional analysis techniques such as probability random variables distribution functions and density functions Probability models and random processes are also discussed Noise representation sources noise factor noise temperature filtering of noise noise bandwidth and performance of AM FM in presence of noise is discussed in fourth chapter Analog pulse modulation is presented in fifth chapter Sampling PAM PAM TDM are discussed in this chapter Sixth chapter deals with digital pulse modulation methods such as PCM DM ADM and DPCM Seventh chapter presents digital multiplexers line coding synchronization scramblers ISI eye patterns and equalization techniques Digital modulation is presented in eighth chapter Phase shift keying frequency shift keying QPSK QAM and MSK are presented Last chapter deals with error performance of these techniques using matched filter

Microprocessors & Microcontrollers Atul P. Godse, Dr. Deepali A. Godse, 2021-01-01 The book is written for an undergraduate course on the 8086 microprocessor and 8051 microcontroller It provides comprehensive coverage of the hardware and software aspects of 8086 microprocessor and 8051 microcontroller The book is divided into three parts The first part focuses on 8086 microprocessor It teaches you the 8086 architecture instruction set Assembly Language Programming ALP interfacing 8086 with support chips memory and peripherals such as 8251 8253 8255 8259 8237 and 8279 It also explains the interfacing of 8086 with data converters ADC and DAC and introduces a traffic light control system The second part focuses on multiprogramming and multiprocessor configurations numeric processor 8087 I/O processor 8089 and introduces features of advanced processors such as 80286 80386 80486 and Pentium processors The third part focuses on 8051 microcontroller It teaches you the 8051 architecture instruction set programming 8051 and interfacing 8051 with external memory It explains timers counters serial port interrupts of 8051 and their programming It also describes the interfacing 8051 with data converters ADC and DAC keyboards LCDs LEDs stepper motors and sensors Digital Signal

Processing C. Ramesh Babu Durai, 2005-12 **Microprocessors & Introduction to Microcontroller** Atul P. Godse, Dr. Deepali A. Godse, 2020-12-01 The book is written for an undergraduate course on the 8085 and 8086 microprocessors and 8051 microcontroller It provides comprehensive coverage of the hardware and software aspects of 8085 and 8086 microprocessors and 8051 microcontroller The book uses plain and lucid language to explain each topic A large number of programming examples is the feature of this book The book provides the logical method of describing the various complicated concepts and stepwise techniques for easy understanding making the subject more interesting The book is divided into three parts The first part focuses on the 8085 microprocessor It teaches you the 8085 architecture pin description bus organization instruction set addressing modes instruction formats Assembly Language Programming ALP instruction timing diagrams interrupts and interfacing 8085 with support chips memory and peripheral ICs 8251 8253 8255 8259 and 8279 It also explains the interfacing of 8085 with data converters ADC and DAC and introduces a temperature control system design The second part focuses on the 8086 microprocessor It teaches you the 8086 architecture register organization memory segmentation interrupts addressing modes operating modes minimum and maximum modes interfacing 8086 with support chips minimum and maximum mode 8086 systems and timings The third part focuses on the 8051 microcontroller It teaches you the 8051 architecture pin description instruction set programming 8051 and interfacing 8051 with external memory It explains timers counters serial port interrupts of 8051 and their programming It also describes the interfacing 8051 with keyboards LCDs and LEDs and explains the control of servomotor stepper motors and washing machine using 8051 **Department of Defense appropriations for 1982** United States. Congress. House. Committee on Appropriations. Subcommittee on Department of Defense, 1981 **Control System Theory** Uday A. Bakshi, 2020-12-01 The book is written for an undergraduate course on the theory of Feedback Control Systems It provides comprehensive explanation of theory and practice of control system engineering It elaborates various aspects of time domain and frequency domain analysis and design of control systems Each chapter starts with the background of the topic Then it gives the conceptual knowledge about the topic dividing it in various sections and subsections Each chapter provides the detailed explanation of the topic practical examples and variety of solved problems The explanations are given using very simple and lucid language All the chapters are arranged in a specific sequence which helps to build the understanding of the subject in a logical fashion The book starts with explaining the various types of control systems Then it explains how to obtain the mathematical models of various types of systems such as electrical mechanical thermal and liquid level systems Then the book includes good coverage of the block diagram and signal flow graph methods of representing the various systems and the reduction methods to obtain simple system from the analysis point of view The book further illustrates the steady state and transient analysis of control systems The book covers the fundamental knowledge of controllers used in practice to optimize the performance of the systems The book emphasizes the detailed analysis of second order systems as these systems

are common in practice and higher order systems can be approximated as second order systems The book teaches the concept of stability and time domain stability analysis using Routh Hurwitz method and root locus method It further explains the fundamentals of frequency domain analysis of the systems including co relation between time domain and frequency domain The book gives very simple techniques for stability analysis of the systems in the frequency domain using Bode plot Polar plot and Nyquist plot methods It also explores the concepts of compensation and design of the control systems in time domain and frequency domain The classical approach loses the importance of initial conditions in the systems Thus the book provides the detailed explanation of modern approach of analysis which is the state variable analysis of the systems including methods of finding the state transition matrix solution of state equation and the concepts of controllability and observability The book also introduces the concept of discrete time systems including digital and sample data systems z transform difference equations state space representation pulse transfer functions and stability of linear discrete time systems The variety of solved examples is the feature of this book which helps to inculcate the knowledge of the design and analysis of the control systems in the students The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting

Department of Defense Appropriations United States. Congress. House. Committee on Appropriations. Subcommittee on Department of Defense,1982 **Department of Defense Appropriations for 1982: Tactical aircraft and missile programs** United States. Congress. House. Committee on Appropriations. Subcommittee on Department of Defense,1981 *Department of Defense Appropriations for ...* United States. Congress. House. Committee on Appropriations,1981 *Railway Signal* ,1892 **Signals** ,1984 Methods of Discrete Signal and System Analysis Mark T. Jong,1982 Official Gazette of the United States Patent and Trademark Office ,2002 Technical News Bulletin of the National Bureau of Standards ,1959 American Stationer and Office Manager ,1918 *Soft Computing and Signal Processing* Jiacun Wang,G. Ram Mohana Reddy,V. Kamakshi Prasad,V. Sivakumar Reddy,2019-02-13 The book includes research papers on current developments in the field of soft computing and signal processing selected from papers presented at the International Conference on Soft Computing and Signal Processing ICSCSP 2018 It features papers on current topics such as soft sets rough sets fuzzy logic neural networks genetic algorithms and machine learning It also discusses various aspects of these topics like technologies product implementation and application issues **Technical News Bulletin** United States. National Bureau of Standards,1958 *Technical News Bulletin* ,1959 *Dimensions* ,1958

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