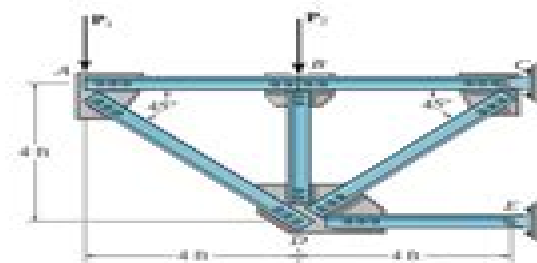


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6-2. The truss, used to support a balcony, is subjected to the loading shown. Approximate each joint as a pin and determine the force in each member. State whether the members are in tension or compression. Set $P_1 = 600$ lb, $P_2 = 400$ lb.



Joint A :

$$+\circlearrowleft \sum M_j = 0; \quad F_{AD} \sin 45^\circ - 600 = 0$$

$$F_{AD} = 848.528 = 849 \text{ lb (C)} \quad \text{Ans}$$

$$+\rightarrow \sum F_x = 0; \quad F_{AB} - 848.528 \cos 45^\circ = 0$$

$$F_{AB} = 600 \text{ lb (T)} \quad \text{Ans}$$



Joint B :

$$+\circlearrowleft \sum M_j = 0; \quad F_{BD} - 400 = 0$$

$$F_{BD} = 400 \text{ lb (C)} \quad \text{Ans}$$

$$+\rightarrow \sum F_x = 0; \quad F_{BE} - 400 = 0$$

$$F_{BE} = 400 \text{ lb (T)} \quad \text{Ans}$$



Joint D :

$$+\circlearrowleft \sum M_j = 0; \quad F_{DE} \sin 45^\circ - 400 - 848.528 \sin 45^\circ = 0$$

$$F_{DE} = 1414.214 \text{ lb} = 1.41 \text{ kip (T)} \quad \text{Ans}$$

$$+\rightarrow \sum F_x = 0; \quad 848.528 \cos 45^\circ + 1414.214 \cos 45^\circ - F_{AD} = 0$$

$$F_{AD} = 1600 \text{ lb} = 1.60 \text{ kip (C)} \quad \text{Ans}$$



Statics Hibbeler Chapter 6

Richard C Dorf



Statics Hibbeler Chapter 6:

Engineering Mechanics--statics and Dynamics R. C. Hibbeler, 1995 This best selling book offers a concise and thorough presentation of engineering mechanics theory and application The material is reinforced with numerous examples to illustrate principles and imaginative well illustrated problems of varying degrees of difficulty The book is committed to developing its users problem solving skills and includes pedagogical features that have made Hibbeler synonymous with excellence in the field Chapter topics cover general principles force vectors equilibrium of a particle force system resultants equilibrium of a rigid body structural analysis internal forces friction center of gravity and centroid moments of inertia virtual work kinematics of a particle kinetics of a particle force and acceleration kinetics of a particle work and energy kinetics of a particle impulse and momentum planar kinematics of a rigid body planar kinetics of a rigid body force and acceleration planar kinetics of a rigid body work and energy planar kinetics of a rigid body impulse and momentum three dimensional kinematics of a rigid body three dimensional kinetics of a rigid body and vibrations For individuals involved in the study of mechanical civil aeronautical engineering Engineering Mechanics: Statics R. C. Hibbeler, 1974 **Fundamentals of Manufacturing, Third Edition** Philip D. Rufe, 2013 Fundamentals of Manufacturing Third Edition provides a structured review of the fundamentals of manufacturing for individuals planning to take SME S Certified Manufacturing Technologist CMfgT or Certified Manufacturing Engineer CMfgE certification exams This book has been updated according to the most recent Body of Knowledge published by the Certification Oversight and Appeals Committee of the Society of Manufacturing Engineers While the objective of this book is to prepare for the certification process it is a primary source of information for individuals interested in learning fundamental manufacturing concepts and practices This book is a valuable resource for anyone with limited manufacturing experience or training Instructor slides and the Fundamentals of Manufacturing Workbook are available to complement course instruction and exam preparation Table of Contents Chapter 1 Mathematics Chapter 2 Units of Measure Chapter 3 Light Chapter 4 Sound Chapter 5 Electricity Electronics Chapter 6 Statics Chapter 7 Dynamics Chapter 8 Strength of Materials Chapter 9 Thermodynamics and Heat Transfer Chapter 10 Fluid Power Chapter 11 Chemistry Chapter 12 Material Properties Chapter 13 Metals Chapter 14 Plastics Chapter 15 Composites Chapter 16 Ceramics Chapter 17 Engineering Drawing Chapter 18 Geometric Dimensioning and Tolerancing Chapter 19 Computer Aided Design Engineering Chapter 20 Product Development and Design Chapter 21 Intellectual Property Chapter 22 Product Liability Chapter 23 Cutting Tool Technology Chapter 24 Machining Chapter 25 Metal Forming Chapter 26 Sheet Metalworking Chapter 27 Powdered Metals Chapter 28 Casting Chapter 29 Joining and Fastening Chapter 30 Finishing Chapter 31 Plastics Processes Chapter 32 Composite Processes Chapter 33 Ceramic Processes Chapter 34 Printed Circuit Board Fabrication and Assembly Chapter 35 Traditional Production Planning and Control Chapter 36 Lean Production Chapter 37 Process Engineering Chapter 38 Fixture and Jig Design Chapter 39 Materials Management Chapter 40 Industrial

Safety Health and Environmental Management Chapter 41 Manufacturing Networks Chapter 42 Computer Numerical Control Machining Chapter 43 Programmable Logic Controllers Chapter 44 Robotics Chapter 45 Automated Material Handling and Identification Chapter 46 Statistical Methods for Quality Control Chapter 47 Continuous Improvement Chapter 48 Quality Standards Chapter 49 Dimensional Metrology Chapter 50 Nondestructive Testing Chapter 51 Management Introduction Chapter 52 Leadership and Motivation Chapter 53 Project Management Chapter 54 Labor Relations Chapter 55 Engineering Economics Chapter 56 Sustainable Manufacturing Chapter 57 Personal Effectiveness

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Theory of Gyroscopic Effects for Rotating Objects Ryspek

Usubamatov, 2022-06-30 This book highlights an analytical solution for the dynamics of axially rotating objects It also presents the theory of gyroscopic effects explaining their physics and using mathematical models of Euler's form for the motion of movable spinning objects to demonstrate these effects The major themes and approaches are represented by the spinning disc and the action of the system of interrelated inertial torques generated by the centrifugal and Coriolis forces as well as the change in the angular momentum The interrelation of inertial torques is based on the dependency of the angular velocities of the motions of the spinning objects around axes by the principle of mechanical energy conservation These kinetically interrelated torques constitute the fundamental principles of the mechanical gyroscope theory that can be used for any rotating objects of different designs like rings cones spheres paraboloids propellers etc Lastly the mathematical models for the gyroscopic effects are validated by practical tests The 2nd edition became necessary due to new development and corrections of mathematical expressions It contains new chapters about the Tippe top inversion and inversion of the spinning object in an orbital flight and the boomerang aerodynamics

Statics and Mechanics of Materials R. C. Hibbeler, 1993 A comprehensive and well illustrated introduction to theory and application of statics and mechanics of materials FEATURES Features an abundance of imaginative well illustrated problems and examples Pedagogical features include chapter objectives boxed equations and bolded headings and sub headings The book is paginated so topics and

examples appear on facing pages eliminating the need to keep flipping pages back and forth Includes advanced material such as inelastic loadings stress concentrations residual stress stresses in curved and composite beams and energy methods New to this edition 20 % NEW problems categorization of homework problems as basic challenging computer applications and design oriented NEW design problems FIT exam review problems enhancement of free body diagram concept photographs added to enhance the realism of the book

Friction Science and Technology Peter J. Blau, 2008-10-20 Should have broad appeal in many kinds of industry ranging from automotive to computers basically any organization concerned with products having moving parts David A Rigney Materials Science and Engineering Department Ohio State University Columbus USA In Depth Coverage of Frictional Concepts Friction affects so many aspects of daily life

Mechanics for Engineers R. C. Hibbeler, 1985

Kinematics and Dynamics of Mechanical Systems Kevin Russell, John Q. Shen, Raj Sodhi, 2022-12-16 Updated throughout for the third edition Kinematics and Dynamics of Mechanical Systems Implementation in MATLAB and Simscape Multibody™ offers step by step instructions on the fundamentals of mechanism kinematics synthesis statics and dynamics alongside demonstrating its real world applications Following updates made by MATLAB replacing Simmechanics with new system Simscape Multibody this textbook provides updated instructions and example problems to fully enable the reader to use this new and improved system New features discussed in the book include enhanced rendering 3D geometry in animations of user generated solutions for planar linkages spatial linkages and robotic systems The textbook provides the perfect companion to aid students in analyzing and designing mechanical systems The book will be of interest to students and professional in the field of automotive engineering mechatronics and robotics with a special focus on kinematics dynamics and machine design

Statics Study Pack R. C. Hibbeler, Peter Schiavone, 2004 This workbook is divided into two parts Part 1 provides a section by section chapter by chapter summary of the key concepts principles and equations from R C Hibbeler's text Engineering Mechanics Statics 10th ed Part 2 is a workbook which explains how to draw and use free body diagrams when solving problems in Statics

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