1.28. (a) Linear, stable.

(b) Time invariant, linear, causal, stable.

(c) Memoryless, linear, causal.

(d) Linear, stable.

(e) Linear, stable.

(f) Memoryless, linear, causal, stable.

(g) Linear, stable.

1.29. (a) Consider two inputs to the system such that

$$x_1[n] \xrightarrow{S} y_1[n] = \Re e\{x_1[n]\} \quad \text{and} \quad x_2[n] \xrightarrow{S} y_2[n] = \Re e\{x_2[n]\}.$$

Now consider a third input $x_3[n] = x_1[n] + x_2[n]$. The corresponding system output will be

$$
\begin{aligned}
y_3[n] &= \Re e\{x_3[n]\} \\
&= \Re e\{x_1[n] + x_2[n]\} \\
&= \Re e\{x_1[n]\} + \Re e\{x_2[n]\} \\
&= y_1[n] + y_2[n].
\end{aligned}
$$

Therefore, we may conclude that the system is additive.

Let us now assume that the input-output relationship is changed to $y[n] = \Re e\{e^{j\pi n/4}x[n]\}$. Also, consider two inputs to the system such that

$$x_1[n] \xrightarrow{S} y_1[n] = \Re e\{e^{j\pi n/4}x_1[n]\}$$

and

$$x_2[n] \xrightarrow{S} y_2[n] = \Re e\{e^{j\pi n/4}x_2[n]\}.$$
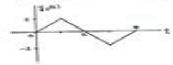
Now consider a third input $x_3[n] = x_1[n] + x_2[n]$. The corresponding system output will be

$$
\begin{aligned}
y_3[n] &= \Re e\{e^{j\pi n/4}x_3[n]\} \\
&= \cos(\pi n/4)\Re e\{x_1[n] + x_2[n]\} - \sin(\pi n/4)\Im m\{x_1[n] + x_2[n]\} \\
&= \cos(\pi n/4)\Re e\{x_1[n]\} - \sin(\pi n/4)\Im m\{x_1[n]\} \\
&\quad + \cos(\pi n/4)\Re e\{x_2[n]\} - \sin(\pi n/4)\Im m\{x_2[n]\} \\
&= \Re e\{e^{j\pi n/4}x_1[n]\} + \Re e\{e^{j\pi n/4}x_2[n]\} \\
&= y_1[n] + y_2[n].
\end{aligned}
$$

Therefore, we may conclude that the system is additive.

13

(b) (i) Consider two inputs to the system such that

$$x_1(t) \xrightarrow{S} y_1(t) = \frac{1}{x_1(t)}\left[\frac{dx_1(t)}{dt}\right]^2 \quad \text{and} \quad x_2(t) \xrightarrow{S} y_2(t) = \frac{1}{x_2(t)}\left[\frac{dx_2(t)}{dt}\right]^2.$$

Now consider a third input $x_3(t) = x_1(t) + x_2(t)$. The corresponding system output will be

$$
\begin{aligned}
y_3(t) &= \frac{1}{x_3(t)}\left[\frac{dx_3(t)}{dt}\right]^2 \\
&= \frac{1}{x_1(t) + x_2(t)}\left[\frac{dx_1(t) + x_2(t)}{dt}\right]^2 \\
&\ne y_1(t) + y_2(t).
\end{aligned}
$$

Therefore, we may conclude that the system is not additive.

Now consider a fourth input $x_4(t) = ax_1(t)$. The corresponding output will be

$$
\begin{aligned}
y_4(t) &= \frac{1}{x_4(t)}\left[\frac{dx_4(t)}{dt}\right]^2 \\
&= \frac{1}{ax_1(t)}\left[\frac{dax_1(t)}{dt}\right]^2 \\
&= \frac{a}{x_1(t)}\left[\frac{dx_1(t)}{dt}\right]^2 \\
&= ay_1(t).
\end{aligned}
$$

Therefore, the system is homogeneous.

(ii) The system is not additive. Consider the following example. Let $x_1[n] = 2\delta[n+2] + 2\delta[n+1] + 2\delta[n]$ and $x_2[n] = \delta[n+2] + 2\delta[n+1] + 3\delta[n]$. The corresponding outputs evaluated at $n = 0$ are

$$y_1[0] = 2 \quad \text{and} \quad y_2[0] = 3/2.$$

Now consider a third input $x_3[n] = x_1[n] + x_2[n] = 3\delta[n+2] + 4\delta[n+1] + 5\delta[n]$. The corresponding output evaluated at $n = 0$ is $y_3[0] = 16/4$. Clearly, $y_3[0] \ne y_1[0] + y_2[0]$. This implies that the system is not additive.

Now consider an input $x_4[n]$ which leads to the output $y_4[n]$. We know that

$$x_4[n] = \begin{cases} \frac{x_4[n]x_4[n-2]}{x_4[n-1]}, & x_4[n-1] \ne 0 \\ 0, & \text{otherwise} \end{cases}$$

Let us now consider another input $x_5[n] = ax_4[n]$. The corresponding output is

$$y_5[n] = \begin{cases} \frac{x_5[n]x_5[n-2]}{x_5[n-1]}, & x_5[n-1] \ne 0 \\ 0, & \text{otherwise} \end{cases} = ay_4[n].$$

Therefore, the system is homogeneous.

14

(iii) False. $y[n]$ periodic does not imply $x[n]$ is periodic. i.e. let $x[n] = \begin{cases} 1, & n \text{ even} \\ 0, & n \text{ odd} \end{cases}$ and $x_2[n] = \begin{cases} 0, & n \text{ even} \\ 1/2^n, & n \text{ odd} \end{cases}$

Then $y_1[n] = x[n]$ is periodic but $x[n]$ is clearly not periodic.

(iv) True. $x[n+N] = x[n]$, $y_1[n+N_1] = y_1[n]$ where $N_1 = 2M$.

(v) True. $x[n+N] = x[n]$, $y_1[n+N_1] = x[n]$ where $N_1 = N/2$.

1.34. (a) Consider

$$\sum_{n=-\infty}^{\infty} x[n] = x[0] + \sum_{n=1}^{\infty} \{x[n] + x[-n]\}.$$

If $x[n]$ is odd, $x[0] + x[-n] = 0$. Therefore, the given summation evaluates to zero.

(b) Let $y[n] = x_1[n]x_2[n]$. Then

$$y[-n] = x_1[-n]x_2[-n] = -x_1[n]x_2[n] = -y[n].$$

This implies that $y[n]$ is odd.

(c) Consider

$$
\begin{aligned}
\sum_{n=-\infty}^{\infty} x^2[n] &= \sum_{n=-\infty}^{\infty} \{x_e[n] + x_o[n]\}^2 \\
&= \sum_{n=-\infty}^{\infty} x_e^2[n] + \sum_{n=-\infty}^{\infty} x_o^2[n] + 2\sum_{n=-\infty}^{\infty} x_e[n]x_o[n].
\end{aligned}
$$

Using the result of part (b), we know that $x_e[n]x_o[n]$ is an odd signal. Therefore, using the result of part (a) we may conclude that

$$2\sum_{n=-\infty}^{\infty} x_e[n]x_o[n] = 0.$$

Therefore,

$$\sum_{n=-\infty}^{\infty} x^2[n] = \sum_{n=-\infty}^{\infty} x_e^2[n] + \sum_{n=-\infty}^{\infty} x_o^2[n].$$

(d) Consider

$$\int_{-\infty}^{\infty} x^2(t)dt = \int_{-\infty}^{\infty} x_e^2(t)dt + \int_{-\infty}^{\infty} x_o^2(t)dt + 2\int_{-\infty}^{\infty} x_e(t)x_o(t)dt.$$

Again, since $x_e(t)x_o(t)$ is odd,

$$\int_{-\infty}^{\infty} x_e(t)x_o(t)dt = 0.$$

Therefore,

$$\int_{-\infty}^{\infty} x^2(t)dt = \int_{-\infty}^{\infty} x_e^2(t)dt + \int_{-\infty}^{\infty} x_o^2(t)dt.$$

16

1.30. (a) Invertible. Inverse system: $y(t) = x(t) + 4$.

(b) Non-invertible. The signals $x(t)$ and $x_1(t) = x(t) + 2\pi$ give the same output.

(c) Non-invertible. $\delta[n]$ and $2\delta[n]$ give the same output.

(d) Invertible. Inverse system: $y(t) = dx(t)/dt$.

(e) Invertible. Inverse system: $y[n] = x[n+1]$ for $n \ge 0$ and $y[n] = x[n]$ for $n < 0$.

(f) Non-invertible. $x[n]$ and $-x[n]$ give the same result.

(g) Invertible. Inverse system: $y[n] = x[-n]$.

(h) Invertible. Inverse system: $y(t) = dx(t)/dt$.

(i) Invertible. Inverse system: $y[n] = x[n] - (1/2)x[n-1]$.

(j) Non-invertible. If $x(t)$ is any constant, then $y(t) = 0$.

(k) Non-invertible. $\delta[n]$ and $2\delta[n]$ result in $y[n] = 0$.

(l) Invertible. Inverse system: $y(t) = x(t/2)$.

(m) Non-invertible. $x_1[n] = \delta[n] + \delta[n-1]$ and $x_2[n] = \delta[n]$ give $x_1[n] = x[n] - \delta[n]$.

(n) Invertible. Inverse system: $y[n] = x[2n]$.

1.31. (a) Note that $x_2(t) = x_1(t) - x_1(t-2)$. Therefore, using linearity we get $y_2(t) = y_1(t) - y_1(t-2)$. This is as shown in Figure S1.31.

(b) Note that $x_3(t) = x_1(t) + x_1(t+1)$. Therefore, using linearity we get $y_3(t) = y_1(t) + y_1(t+1)$. This is as shown in Figure S1.31.

Figure S1.31.

1.32. All statements are true.

(1) $x(t)$ periodic with period T. $y(t)$ periodic, period $T/2$.

(2) $y(t)$ periodic, period T. $x(t)$ periodic, period $2T$.

(3) $x(t)$ periodic, period T. $y(t)$ periodic, period $2T$.

(4) $x(t)$ periodic, period T. $y(t)$ periodic, period $T/2$.

1.33. (1) True. $x[n] = x[n+N]$, $y[n] = y[n+N]$. i.e. periodic with $N_1 = N/2$ if N is even, and with period $N_1 = N$ if N is odd.

15

Signals And Systems Nawab Solution Manual

Tao Wei

Signals And Systems Nawab Solution Manual:

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Table of Contents Signals And Systems Nawab Solution Manual

1. Understanding the eBook Signals And Systems Nawab Solution Manual
    - The Rise of Digital Reading Signals And Systems Nawab Solution Manual
    - Advantages of eBooks Over Traditional Books
2. Identifying Signals And Systems Nawab Solution Manual
    - Exploring Different Genres
    - Considering Fiction vs. Non-Fiction
    - Determining Your Reading Goals
3. Choosing the Right eBook Platform
    - Popular eBook Platforms
    - Features to Look for in an Signals And Systems Nawab Solution Manual
    - User-Friendly Interface
4. Exploring eBook Recommendations from Signals And Systems Nawab Solution Manual
    - Personalized Recommendations
    - Signals And Systems Nawab Solution Manual User Reviews and Ratings
    - Signals And Systems Nawab Solution Manual and Bestseller Lists
5. Accessing Signals And Systems Nawab Solution Manual Free and Paid eBooks

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